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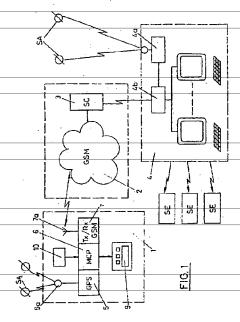
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(54) Safety system for vehicles

Safety system for vehicles, applicable to transmitting information from a vehicle confronted with emergency conditions to a control centre, in such a way that the latter is able to locate the position of the said vehicle and to take the appropriate decisions. The system makes use of a device which sends/receives digital messages to or from a control centre via the GSM communications system. The said messages contain information relating to the position of the vehicle and are generated in response to a message coming from the control centre or by activation of alarm means which are provided in the vehicle. The control centre thus has available the relevant information on the vehicles and on the geographical area covered by the system and can process it jointly with the information transmitted to the vehicle and/or received therefrom.

The interchange of information between the control centre and the vehicle or vehicles takes place in the form of short data messages through the short message service of the GSM network, with the intervention of a service centre of the said network for storing and distributing the said short messages.



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Description

The present invention relates to safety systems and, more particularly, to systems for transmitting information from a vehicle confronted with emergency conditions to a control centre which allows it to locate the position of the vehicle in order to take the appropriate decisions. The system can be activated from the vehicle itself or else from the control centre.

Various systems of this sort are already known, which make it possible to locate the position of a vehicle, for example a stolen or crashed vehicle, making use of tracking systems which take advantage of data received from satellites — GPS receivers (acronym derived from the expression "Global Positioning System") -, by virtue of which it becomes possible to obtain extremely accurate data as to the position and speed of movement of a mobile, which can be transmitted through a given radio-transmitter device to a work station in which the information received is processed in an appropriate form.

In this respect, the following European patent applications are cited as representative of the prior art: EP 0 242 099, EP 0 512 789, EP 0 350 554, EP 0 559 074 and the PCT document WO 93/05490.

In these documents are described various alarm signal generator systems for vehicles, which are intended, from the GPS system, to obtain data relating to the position and speed of a vehicle, as well as data relating to time and date, and to transmit the said datato a central control station, generally by means of a radio link.

The systems described, having the common feature of using GPS systems to locate the position of a vehicle, vary according to the specific objectives of the system and according to the communications technique used to interchange information between the vehicle and the control centre.

Unlike what is described in the prior art, the system which is the subject of the present invention uses the GSM communications system as a transmission means between the mobile and the control centre, and is configured in such a way that its cost makes it viable for large-scale installation as a safety system for motor vehicles, which is an objective which is difficult to achieve with the known systems. More particularly, in the present invention, the SMS facility (Short Message Service) is used which the GSM communications system offers and which allows low-speed data transmission without the necessity of using network resources (no subscriber terminal channel being necessary), using solely the signalling system which has a reduced cost.

In consequence, a subject of the invention is the production of the system which is the subject of Claim 1 and of the claims dependent on it, which implies installation and operation costs which are very much less than those of the systems of the prior art.

A further subject of the invention is the device which is the subject of Claim 4. This device, located in the vehicle, is the central element of the system.

In what follows, a preferred embodiment of the invention will be described, making reference for that purpose to the attached drawings, in which:

Fig. 1 is a diagrammatic representation of the architecture of the system in accordance with the invention:

Fig. 2 is a diagram which represents only the architecture of the unit which is to be mounted in a vehicle which incorporates the subject of the invention; Fig. 3 is a diagram of the communications module; and

Fig. 4 diagrammatically represents the basic structure of the GSM network used in the system of Fig.

Referring now to the drawings, and in particular to Fig. 1 thereof, the unit to be installed in each vehicle (from now on VTU - Vehicle Terminal Unit -) is there designated overall as 1; a detailed description of the unit will be given later, referring to Fig. 2. The GSM mobile communications network is designated diagrammatically as 2, this network offering the short message service, which, as has been said, allows bidirectional low-speed data communication between the control centre 4 and the VTU via the centre 3, which is responsible for receiving and sending the short messages, from the VTU/control centre or control centre/VTU origin.

The satellites SA send coded digital signals which are received by the antenna 5a of the global positioning system (GPS) receiver. These same satellites are used in the service control centre 4 to generate reference signals which are received in the receiver 4a and sent to the communications manager 4b of the said centre for functions of adjustment and correction of the signals received from the VTUs in order to obtain a more precise position of the mobile from the GPS system.

From the control centre 4, which incorporates the vehicle location services, communications can moreover be set up with various services SE such as police, medical assistance and/or technical assistance.

Referring now to Fig. 2 of the drawings, the VTU is there represented installed in a vehicle which incorporates the system of the invention, and consisting of:

- a) a GPS receiver 5, which comprises a receiving antenna 5a and a reception and control microcontroller (not illustrated), which supplies the positioning coordinates. This receiver can be of any commercially available type, being connected with the control and processing module 6 through a serial RS-232 channel;
- b) a control and processing module (MCP) 6, intended to control the position determination element (GPS receiver) 5, as well as the communications means 7 (GSM module in short-message mode) which are used for information interchange with the Vehicle Location Service Control Centre

c) a communications module 7, based on a transmitter/receiver (Tx/Rx), which fulfils the function of interconnection with the GSM communications system 2, at the same time as it manages the transmission/reception of orders in short-message format; this communications module 7, equipped with an antenna 7a, consists of a radiofrequency unit 11, which fulfils the functions of antenna filter, receiver, transmitter, receiver and tuner (RX, TX, SI), and a processing and base band controller unit 12, which fulfils the function of channel coder/decoder and which incorporates the communications and protocol software which supports the functionality of the 20 short-message service. This base band controller is connected, via an asynchronous channel CA, with the control and processing module 6.

Moreover, in Fig. 4 is shown the basic structure of the GSM mobile communications network. The acronyms included in the said figure have the following

MS SMS SME

SC

- Network terminal mobile station
- Short-message (SM) transmission service
- Entity with the capacity for sending and receiving short messages. This can be located in the fixed network, on a mobile or at a shortmessage service centre

- System responsible for storing and distributing short messages between an SME and an MS

MSC Mobile services switching centre

- Public mobile telephone network for land-PLMN based service

Moreover, means (SMS-GMSC) are provided for interconnecting with the service centre (SC) which are intended to support the short-message service which is terminated at the mobile, and others (SMS-IWMSC) which are intended to fulfil the function of interconnecting with the service centre (SC) for the purpose of supporting the short-message service for messages originating at the mobile.

Via the SMS service (Short Message Service) of the said network, a link is established for transmitting lowspeed data between the Control Centre and the VTU which allows bidirectional transmission of information relating to the positioning and to the alarms generated in the said mobile unit from the latter to the said Control Centre in the form of messages of limited size; with the object of supporting this service, use is made of a Short

Message Service Centre, designated as 3 in Fig. 1, which acts as a medium for storing and sending said short messages

Consequently, the GSM network operates as an information transport system between the Service Centre and the VTUs.

Finally, the Control Centre 4 consists, at the operating level, of a communications manager 4b, a GPS receiver for reference signals 4a and a local area network to which the computers are connected (preferably personal computers with a high-throughput processor), which support the graphics screens of the operator stations, the network server computer which contains all the information databases, as well as the communications manager itself. The local area network uses Windows NT (registered trademark of Microsoft Corp.) as operating system.

At the functional level, the control centre consists of the following units:

- communications manager,
 - presentation unit,
 - administration unit.

The communications manager is tasked with managing the reception and the sending of data from and to the mobile units through the Short Message Service Centre, containing the administration unit and the information databases on the mobile units which are incorporated in the system.

For its part, the presentation unit contains the digitalized geographical data and covers an entire operational area, from the level of a street in a town to the level of national boundaries. The presentation system is designed with a windows architecture, so that an operator can view a geographical area in one area of the screen and, at the same time, follow the detailed movement of a vehicle on another map represented in another area of the same visual display screen.

The functions and architecture of the control and processing module (MCP), represented as 6 in Fig. 2, will now be described.

The functions carried out by the MCP are grouped together in the following way:

- initialization functions.
- testing of elements
- acquisition and response to messages from the Control Centre.
- main processing, and
 - attending to the communications.

Initialization of submodules, modules and registers comprises the operations necessary to initialize the positioning submodule and the corresponding communications module, as well as the internal registers, making it possible to establish a defined state every time the MCP 6 is switched on. The said functions are activated every time the module is disconnected from the vehicle power supply and reconnected thereto, for the purpose of establishing the said situation with respect to the Service Control Centre, the first time a communication is set up with the abovementioned Centre, from the change to power supply active, a code is sent which signals the said situation.

The functions of testing and verification of the state of the elements makes it possible to obtain indications as to the operational state of the positioning and communication elements, as well as to establish the initial situation corresponding to the possible incidents which the said elements have (in particular the positioning submodule, since, given the characteristics of the GPS system, parameters have to be taken into account such as the number of satellites visible, reacquisition times, etc.). These functions can be activated automatically, after switching on the module, in a preferred embodiment of the invention.

The functions of acquisition of and response to messages from the Control Centre make it possible to check the validity of the messages received and to give a response to them. In this way, the messages received from the Service Control Centre are authenticated, and the response information is supplied corresponding thereto (fundamentally information relating to the state and to the position of the Control and Processing Module in one embodiment of the invention). For its part, the response information supplied incorporates identification of the Control and Processing Module.

The main processing functions make it possible, with the time delay set and under the programmed conditions (activation of the turn-on signal), to obtain the data relating to position and UTC time, as well as to store the said information in a memory.

Finally, management of the Communications Module (detection of calls and establishment/supervision thereof) covers the functions of handling the communications, by means of the corresponding serial port.

With the aim of achieving reduced production costs and, at the same time, having the necessary flexibility available to adapt the Control and Processing Module to the various customers' requirements, a microprocessor-based architecture has been selected for it, which incorporates a programme memory and data memory in the same integrated circuit, access to the outside world being guaranteed by means of the provision of two serial communications ports, as well as by a generalpurpose transmission line (bus) for expansion, to which peripherals of the usual type can be connected (analogue-to-digital converters, digital or analogue signal multiplexers, sensors, etc.). A GPS submodule, which makes it possible to obtain high-precision timing and positioning information, is directly incorporated on this same line, in module 6.

The requirements which the selected architecture must satisfy are; capability of reprogramming functions by means of software; low production cost; industrial op-

erating temperature range; identification of the module by means of non-copiable firmware, with the aim of avoiding pirating of modules; standard external communication channels (2 FIS-232 channels); means for interconnection with positioning modules, with two capabilities for integration, either directly on the card, or by means of an RS-232 link; and, finally, it must be possible to use, different communication elements through the serial port by virtue of the incorporation of the corresponding software module.

Among the applications of the system in accordance with the invention is the location of stolen vehicles. Activation of the system in this case can be carried out automatically, the electronic security system of the vehicle generating an alarm signal which is sent immediately to the Control Centre together with information relating to the vehicle's position. Obviously, the possibility exists of cancelling the alarm signal generation from the vehicle itself, in which case the customer's key is verified from the said Control Centre.

In this case, the automatic alarm 10 (Fig. 2) detects the incident (unauthorized operation of any of the sensor elements of the alarm system). As a consequence of the said detection, the module 10 (Fig. 2) sends, via the senal line, the code of the alarm generated to the control and processing module (MCP) 6, which produces a short message (160 information bytes) from the alarm code received, adding the positioning information (coordinates) at this precise instant (information received from the GPS receiver module 5) and the instantaneous timing information. The module 6 always includes, in each short message, fixed information consisting of the code of the VTU, the number of the short message service Centre and the number of the Control Centre, the final destination of the said short message.

Next, the module 6 sends the short message produced, through the asynchronous channel CA, to the module 7 (Fig. 2) (GSM transmitter/receiver). The said module 7 has the task of transmitting the short message, making use of the radio unit, through the GSM radio network infrastructure to the Short Message Service Centre (module 3 in Fig. 1) of the said GSM network, which, in its turn, sends the said message to the Control Centre 4 (Fig. 1).

The management application of the Control Centre sends a message to the VTU requesting continuous information on the positioning of the vehicle, so that the sequence which has just been described is repeated automatically every few seconds (a period fixed by the operator), until the operator himself orders the incident to be terminated.

From reception of the message which notifies the theft of the vehicle, the operator sets in train a series of actions such as calling the emergency services closest to the point at which the incident has taken place, calling the vehicle's owner, etc.

For example, the control centre, on receiving the alarm signal, routes it to the first free work station, at the

same time giving a visual and audible alarm until the operator responds. The operator can then watch the situation of the vehicle on the screen, and continue to monitor it, while, in another region of the screen, the data relating to the customer's identification appear, including, for example, a photograph of the vehicle.

Moreover, on the same screen, the operator may have additional information available, relating, for example, to home addresses of the customer close to the alarm, a historical record of action taken or the location of nearby stations of the emergency services.

The alarm message generation can also be performed remotely. For example, an incident may be generated by a telephone call from the vehicle's owner.

In this case, when it is the owner who has detected the theft of the vehicle, he gets in touch with the Control Centre, informing it of the incident. The operator first of all checks the identification code of the person who is calling (with the aim of guaranteeing the validity of the incident), sending a message to the corresponding VTU, if the check proves positive, requesting continuous information on the positioning of the vehicle.

From this moment, the sequence described above is repeated, the VTU sending a short message with the positioning information at a rate fixed by the operator.

A variation of this mode is the requesting, on the part of the user or of an authorized person, of the location of the vehicle.

In another application of the system of the invention, the alarm can be generated manually by the driver of a vehicle by means of a device which is not visible. In this case, the driver pushes a button (theft alarm, medical emergency, breakdown, etc.) on the panel 9 (Fig. 2).

As a consequence of the said button being pushed, the module 9 (Fig. 2) sends the code of the alarm generated, via the serial line, to the control and processing module (MCP) 6, which produces a short message (160 information bytes) from the alarm code received, adding the positioning information (coordinates) at this precise instant (information received from the GPS receiver module 5) and the instantaneous timing information. The module 6 always includes, in each short message, fixed information consisting of the code of the VTÜ, the number of the short message service Centre and the number of the Control Centre, the final destination of the said short message.

Next, the module 6 sends the short message produced, through the asynchronous channel CA, to the module 7 (Fig. 2) (GSM transmitter/receiver). The said module 7 has the task of transmitting the short message, making use of the radio unit, through the GSM radio network infrastructure to the Short Message Service Centre (module 3 in Fig. 1) of the said GSM network, which, in its turn, sends the said message to the Control Centre 4 (Fig. 1).

The management application of the Control Centre sends a message to the VTU requesting continuous information on the positioning of the vehicle, so that the

sequence which has just been described is repeated automatically every few seconds (a period fixed by the operator), until the operator himself orders the incident to be terminated.

Whatever the origin of the alarm message, the Control Centre operator carries out a series of actions which will depend on the type of alarm received, for example, communication with the emergency services closest to the site of the incident, if the alarm received corresponds to attempted theft or assault; connection with medical or ambulance centres closest to the incident if the alarm received corresponds to a medical emergency, or a call to the closest technical assistance centre if the alarm corresponds to technical assistance. In every case, the operator sends a message to the driver, with the action taken, a message which will be presented on the screen of module 9 (Fig. 2).

Finally, the action taken can be permanently archived, the application possibly remaining optionally on hold until a further call is received.

Other applications include, for example, a call for technical or medical assistance, in the event of a break-down or an accident, the alarm message then being sent to the control centre by means of pushing a button on the unit mounted in the vehicle, and the response from the said control centre including the location of nearby medical centres or technical services, respectively, and/or advice to assistance or emergency vehicles, etc.

For their part, the databases managed in the control centre can contain data relating to characteristics and data of the vehicle and of the user of the system, data relating to persons authorized by the user, addresses, telephone numbers of emergency services, historical data of action taken, assistance vehicles, technical services at

Although with the embodiment described the basic usefulness of the invention is rolated to safety, the term being understood in the wide sense, the invention is also applicable for purposes such as route optimization, management of fleets of vehicles, making it possible to track any of them continuously or at intervals. It has already been said, in this context, that the Control and Processing Module is intended to interact with various types of peripherals giving the system great versatility in adapting to various uses.

Although the invention has been described by reference to a preferred embodiment thereof, to the persons skilled in the art there will obviously be numerous changes and modifications of the invention, without in that way departing from the spirit nor from the scope thereof, it is considered that all the abovementioned changes and modifications are included within the scope of the following claims.

Claims

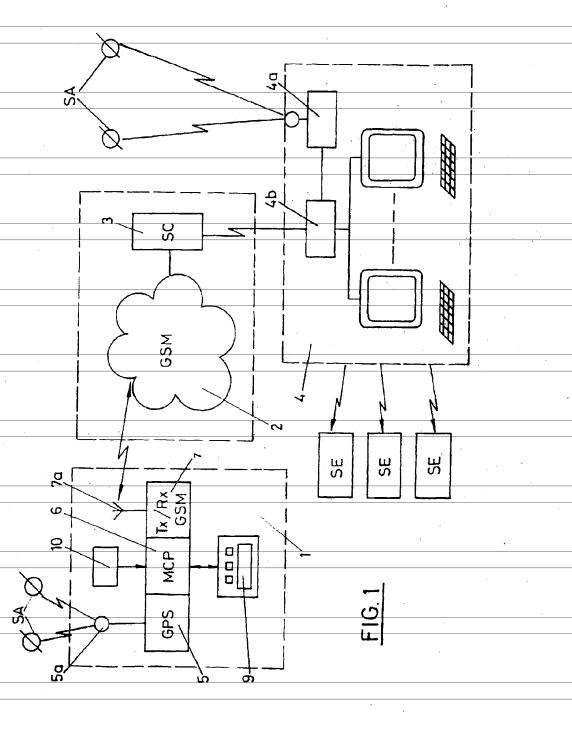
1. Safety system for vehicles which, using a GPS mod-

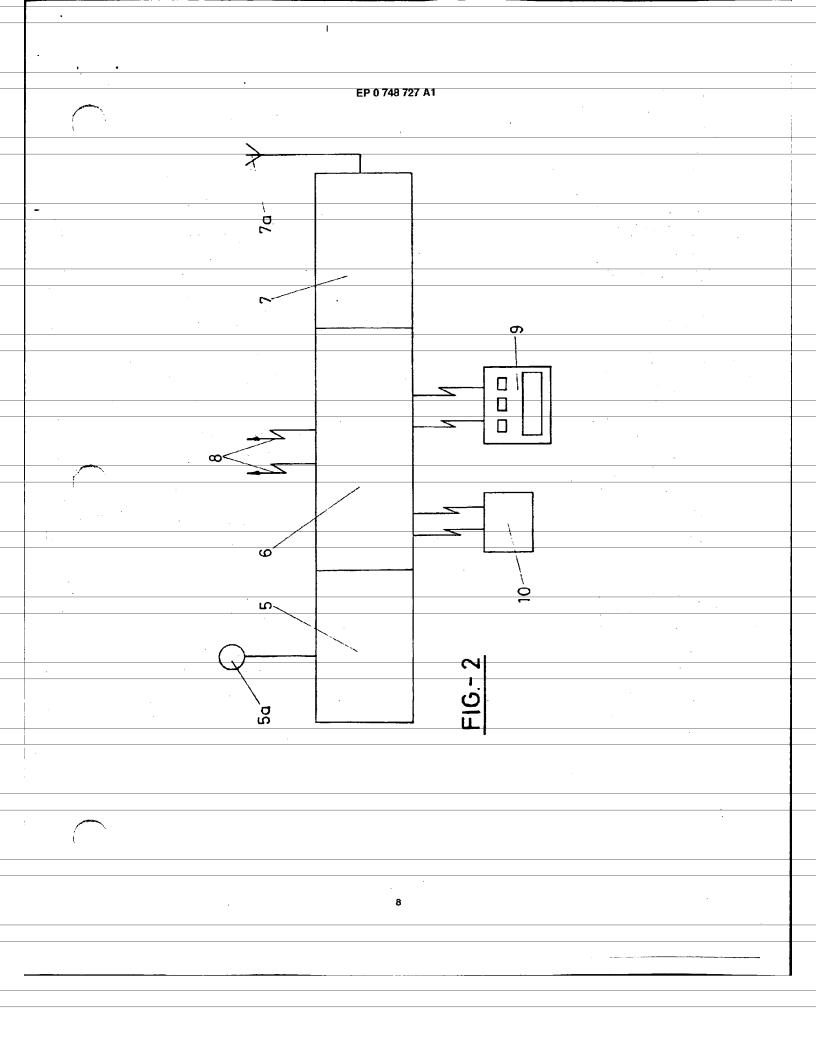
ule for locating the position of the vehicle, is characterized in that it comprises:

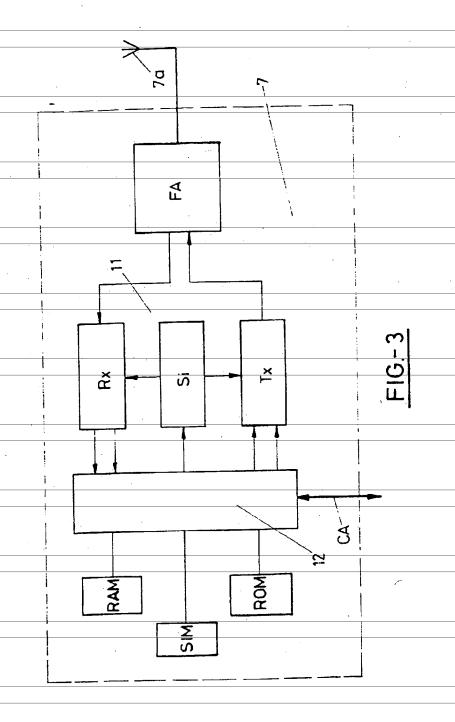
short message service of the GSM network and for being connected to the control and processing module in asynchronous mode.

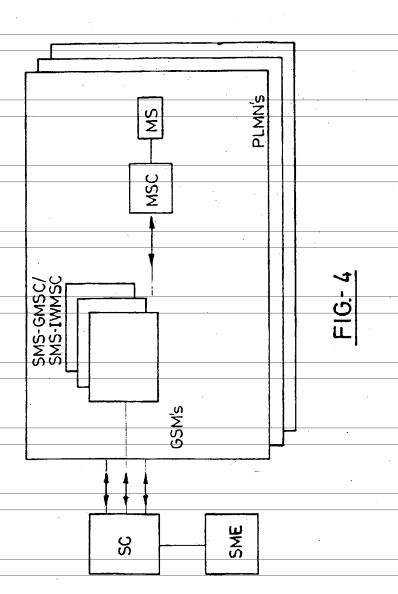
- a) a device situated in the vehicle which sends/
 receives digital messages to/from a control
 centre via the GSM communications system,
 b) means situated in the device for transmitting
 the position of the vehicle to the control centre,
 either in response to a message from the control centre, or by activation of alarm means situated in the device
- c) means situated in the control centre which make it possible to obtain the relevant information from the vehicles and the geographical area covered by the system, and its processing together with the information received/transmitted from/to the vehicle.
- 2. Safety system according to Claim 1, characterized in that the transmission/reception of information between the device of the vehicle and the control centre is carried out in the form of brief data messages, via the short message service of the GSM network, using the support of a short message service centre of the GSM network for storing and distributing the messages.
- 3. Safety system for vehicles, according to the preceding claims, characterized in that the means situated in the control centre comprise a computer system which processes the information received/transmitted from/to the vehicle and that recovered from databases with information on the range of vehicles incorporated in the system and on the geographical area covered by the system, and an interconnection which allows the operator of the control centre to carry out the actions scheduled for each safety function provided by the system.
- 4. Device located in a vehicle for transmitting/receiving information to/from a control centre, consisting of three modules, a GPS receiver Module, a Control and Processing Module, and a communications Module, characterized in that:
 - a) the control and processing Module comprises means for controlling the operation of the GPS receiver module and processing the positional information on the vehicle supplied by the said module in a form suitable for digital transmission thereof,
 - b) the control and processing Module comprises means for transmitting/receiving information to/from devices for automatic processing of information and sensor devices connected to the system.
 - c) the communications Module comprises means for supporting the functionality of the

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EUROPEAN SEARCH REPORT

Application Number EP 96 50 0078

Category	Citation of document with i of relevant pa	odication, where appropriate, ssages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (bLCL6)	·
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	* page 13, line 26-29 * * page 18, line 15 - page 19, line 33 *				
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